

# Linear Algebra I Review

**Final 2002-2:** Consider a system of linear equations with augmented matrix  $C$ .

$$C = \begin{bmatrix} 1 & 0 & 6 & 0 & 0 & 3 & 7 \\ 0 & 1 & 2 & -3 & 0 & 1 & 3 \\ 0 & 2 & 4 & -6 & 2 & 4 & 2 \\ 0 & 0 & 0 & 1 & 0 & -1 & -1 \end{bmatrix}, \quad G = \begin{bmatrix} 1 & 0 & 6 & 0 & 0 & 3 & 7 \\ 0 & 1 & 2 & 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 & 0 & -1 & -1 \\ 0 & 0 & 0 & 0 & 1 & 1 & -2 \end{bmatrix}.$$

Let  $E(i; c)$ ,  $E(i, j)$ , and  $E(i, j; c)$  be elementary matrices of size 4 corresponding to elementary operations  $[i; c]$ ,  $[i, j]$  and  $[i, j; c]$ .

1. We obtained the reduced echelon form  $G$  after applying a sequence of elementary row operations to the matrix  $C$ . Describe each step of a sequence of elementary row operations.
2. Find all solutions of the system of linear equations.
3. Find an invertible matrix  $P$  of size 4 such that  $G = PC$  and express  $P$  as a product of elementary matrices.
4. Show that there is only one  $P$  satisfying the previous problem.
5. Find  $P^{-1}$  and express  $P^{-1}$  as a product of elementary matrices.
6. Find four columns of  $C$  that are linearly dependent (resp. independent).

**Final 2002-5:** Let  $H$  be the coefficient matrix of the system of linear equations given below.

$$\begin{cases} x + y + \lambda z = a \\ \lambda x + y + z = b \\ x + \lambda y + z = c \end{cases}, \quad H = \begin{bmatrix} 1 & 1 & \lambda \\ \lambda & 1 & 1 \\ 1 & \lambda & 1 \end{bmatrix}.$$

1. Find the condition for  $\lambda$  and  $a, b, c$  that the system of linear equations above has infinitely many solutions.
2. Find the condition of  $\lambda$  to satisfy when  $H$  is invertible. Find  $H^{-1}$  for such  $\lambda$ .

**Quiz 2007-6-1:** Consider the equation  $A\mathbf{x} = \mathbf{b}$ , where  $A$ ,  $\mathbf{x}$ ,  $\mathbf{b}$  are as follows.

$$A = \begin{bmatrix} 2 & -2 & -4 & 0 \\ -3 & 5 & 4 & 5 \\ 4 & 2 & -5 & 3 \\ 5 & -7 & -3 & 0 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 3 \\ -2 \\ 1 \\ 0 \end{bmatrix}.$$

1. Evaluate  $\det(A)$ , and determine whether there is no solution, exactly one solution or infinitely many solutions.
2. By Cramer's rule express  $x_3 = \frac{\det(B)}{\det(A)}$  as a fraction of two determinants. Write down the matrix  $B$  in the numerator.
3. Evaluate  $\det(B)$  in the previous problem and find  $x_3$ .

**Special Determinant:**

$$\begin{vmatrix} \lambda & 0 & 0 & \cdots & 0 & c_0 \\ -1 & \lambda & 0 & \cdots & 0 & c_1 \\ 0 & -1 & \lambda & \cdots & 0 & c_2 \\ \vdots & \vdots & \vdots & & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -1 & \lambda + c_{n-1} \end{vmatrix} = c_0 + c_1\lambda + \cdots + c_{n-1}\lambda^{n-1} + \lambda^n.$$

**Review Special Determinants Discussed at a Lecture:**

$$\begin{vmatrix} a & b & b & \cdots & b \\ b & a & b & \cdots & b \\ b & b & a & \cdots & b \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ b & b & b & \cdots & a \end{vmatrix} = (a+(n-1)b)(a-b)^{n-1}, \quad \begin{vmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{n-1} \\ 1 & x_3 & x_3^2 & \cdots & x_3^{n-1} \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ 1 & x_n & x_n^2 & \cdots & x_n^{n-1} \end{vmatrix} = \prod_{i>j} (x_i - x_j).$$

**Cf. Quiz 2010-6-1, 2:** Let  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  be as follows.

$$\mathbf{u} = [5, -2, 1]^\top, \quad \mathbf{v} = [4, -1, 1]^\top, \quad \mathbf{w} = [1, -1, 0]^\top.$$

1. Let  $\theta$  be the angle between  $\mathbf{u}$  and  $\mathbf{v}$ . Find both  $\cos \theta$  and  $\sin \theta$ .
2. Compute  $\mathbf{u} \times \mathbf{v}$  and find a vector of length 1 that is a positive scalar multiple of  $\mathbf{u} \times \mathbf{v}$ .
3. Find the volume of the parallelepiped (*heiko-6-mentai*) in 3-space determined by the vectors  $\mathbf{u}, \mathbf{v}, \mathbf{w}$ .
4. Let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  ( $\mathbf{x} \mapsto \mathbf{u} \times \mathbf{x}$ ). Then  $T$  is a linear transformation. Find the standard matrix of  $T$ .
5. Let  $U : \mathbb{R}^3 \rightarrow \mathbb{R}$  ( $\mathbf{x} \mapsto \mathbf{u} \cdot \mathbf{x}$ ). Then  $U$  is a linear transformation. Find the standard matrix of  $U$ .

**Linear Reflection:** For  $\mathbf{u} = [u_1, u_2, u_3, u_4]^\top$  be a nonzero vector in  $\mathbb{R}^4$ , Let

$$\tau_{\mathbf{u}} : \mathbb{R}^4 \rightarrow \mathbb{R}^4 \left( \mathbf{x} \mapsto \mathbf{x} - \frac{2\mathbf{x} \cdot \mathbf{u}}{\|\mathbf{u}\|^2} \mathbf{u} \right).$$

1. Show that  $\tau_{\mathbf{u}}$  is a linear transformation.
2. Let  $\mathbf{v} = [1, -1, 0, 0]^\top$ . Find the standard matrix of  $\tau_{\mathbf{v}}$ .

**Diagonalization:** Let  $A$  be given below.

$$A = \begin{bmatrix} -1 & -2 & -2 \\ 1 & 2 & 1 \\ -1 & -1 & 0 \end{bmatrix}.$$

1. Find the characteristic polynomial and the eigenvalues of  $A$ .
2. Find  $A^{100}$  and  $A^{25}$ .
3. Find an invertible matrix  $P$  and its inverse  $P^{-1}$  such that  $P^{-1}AP$  is a diagonal matrix.

**To be discussed on November 9, 2017.**

Visit ICU OCW (<http://ocw.icu.ac.jp/majors/mth103-2012a/>), and check Lecture 10 video (After 56'00"), and Lecture 11 video. There is a link from Moodle.) For references, see 'Linear Algebra and Its Applications, Fifth Edition' by David C. Lay