Introduction to Linear Algebra November 17, 2011 Solutions to Final Exam 2011 (Total: 100 pts)

1. Let $T : \mathbb{R}^3 \to \mathbb{R}^3$ be a linear transformation defined by:

$$(15 \text{ pts})$$

$$T(x_1, x_2, x_3) = (2x_1 + 3x_2 + x_3, x_1 - x_2 - x_3, -x_1 + 3x_2 + 5x_3).$$

Let $A = [v_1, v_2, v_3]$ be the standard matrix for the linear transformation T.

(a) Find A. Show work!

Solution. A satisfies the following:

$$A\begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} = \begin{bmatrix} 2x_{1} + 3x_{2} + x_{3} \\ x_{1} - x_{2} - x_{3} \\ -x_{1} + 3x_{2} + 5x_{3} \end{bmatrix}. \text{ For } \boldsymbol{e}_{1} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \boldsymbol{e}_{2} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \boldsymbol{e}_{3} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix},$$
$$\boldsymbol{v}_{1} = [\boldsymbol{v}_{1}, \boldsymbol{v}_{2}, \boldsymbol{v}_{3}] \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = A\boldsymbol{e}_{1} = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix},$$
$$\boldsymbol{v}_{2} = A\boldsymbol{e}_{2} = \begin{bmatrix} 3 \\ -1 \\ 3 \end{bmatrix},$$
$$\boldsymbol{v}_{3} = A\boldsymbol{e}_{3} = \begin{bmatrix} 1 \\ -1 \\ 5 \end{bmatrix}.$$

Thus

$$A = [\boldsymbol{v}_1, \boldsymbol{v}_2, \boldsymbol{v}_3] = \begin{bmatrix} 2 & 3 & 1 \\ 1 & -1 & -1 \\ -1 & 3 & 5 \end{bmatrix}.$$

(b) Find $\boldsymbol{v}_1 \times \boldsymbol{v}_2$. Show work! Solution.

$$\boldsymbol{v}_1 \times \boldsymbol{v}_2 = \left| \begin{array}{ccc} \boldsymbol{e}_1 & \boldsymbol{e}_2 & \boldsymbol{e}_3 \\ 2 & 1 & -1 \\ 3 & -1 & 3 \end{array} \right| = \left[\left| \begin{array}{cccc} 1 & -1 \\ -1 & 3 \end{array} \right|, \left| \begin{array}{cccc} -1 & 2 \\ 3 & 3 \end{array} \right|, \left| \begin{array}{cccc} 2 & 1 \\ 3 & -1 \end{array} \right| \right]^T = \left[\begin{array}{cccc} 2 \\ -9 \\ -5 \end{array} \right]$$

(c) Let $u_1, u_2, u_3 \in \mathbb{R}^3$. Suppose the volume of the parallelepiped determined by u_1, u_2, u_3 is 2. What is the volume of the parallelepiped determined by $T(u_1), T(u_2), T(u_3)$. Write a brief explanation. Solution. Since the volume of the parallelepiped determined by $T(u_1), T(u_2), T(u_3)$ is $|\det(A)|$ times the volume of the parallelepiped determined by u_1, u_2, u_3 , it is

$$|\det(A)| \cdot 2 = |\begin{vmatrix} 2 & 3 & 1 \\ 1 & -1 & -1 \\ -1 & 3 & 5 \end{vmatrix} | \cdot 2 = |\begin{vmatrix} 0 & 5 & 3 \\ 1 & -1 & -1 \\ 0 & 2 & 4 \end{vmatrix} | \cdot 2 = |-14| \cdot 2 = 28.$$

2. Let A and B be the following 4×4 matrices, and $\boldsymbol{b} \in \mathbb{R}^4$ given below. (30 pts)

(a) Find the determinant of A. Show work!

Solution. First apply [1, 2; 1], [1, 3; 1], [1, 4; 1] to columns, eg. add one times the second column to the first, etc. we have

$$\begin{vmatrix} a & b & b & b \\ b & a & b & b \\ b & b & a & b \\ b & b & b & a \end{vmatrix} = \begin{vmatrix} a+3b & b & b & b \\ a+3b & b & a & b \\ a+3b & b & b & a \end{vmatrix} = (a+3b) \begin{vmatrix} 1 & b & b & b \\ 1 & a & b & b \\ 1 & b & a & b \\ 1 & b & b & a \end{vmatrix}$$
$$= (a+3b) \begin{vmatrix} 1 & b & b & b \\ a+3b & b & b & a \end{vmatrix} = (a+3b) \begin{vmatrix} 1 & b & b & b \\ 1 & b & b & a \end{vmatrix} = (a+3b)(a-b)^3.$$

(b) Find the condition that the set of columns of A is linearly <u>dependent</u>. Write a brief explanation.

Solution. The set of columns of A is linearly dependent if and only if $A\mathbf{x} = \mathbf{0}$ has a nontrivial solution. The latter condition is equivalent to A being singular (not invertible). Thus the condition is equivalent to $\det(A) = 0$. Therefore a + 3b = 0 or a = b.

(c) Find the eigenvalues of A, and their multiplicities. Solution. Let f(x) be the characteristic polynomial of A. Then

$$f(x) = \det(A - xI) = \begin{vmatrix} a - x & b & b \\ b & a - x & b & b \\ b & b & a - x & b \\ b & b & b & a - x \end{vmatrix} = ((a - x) + 3b)(a - x - b)^3$$

by replacing a by a - x in the previous problem. Hence

$$f(x) = (x - (a + 3b))(x - (a - b))^3,$$

and a + 3b is an eigenvalue with multiplicity 1 and a - b with multiplicity 3 unless a+3b = a-b, in which case A has only one eigenvalue a with multiplicity 4 and b = 0.

(d) Suppose $b \neq 0$. Find a linearly independent set of vectors $\{v_1, v_2, v_3\}$ such that $Bv_1 = Bv_2 = Bv_3 = 0$. Show that it is actually linearly independent. Solution. By solving the equation Bx = 0 by augmented matrix, we have

Let $\mathbf{v}_1 = [-1, 1, 0, 0]^T$, $\mathbf{v}_2 = [-1, 0, 1, 0]^T$ and $\mathbf{v}_3 = [-1, 0, 0, 1]^T$. If $s\mathbf{v}_1 + t\mathbf{v}_2 + u\mathbf{v}_2 = \mathbf{0}$, then [-s - t - u, s, t, u] = [0, 0, 0, 0]. In this case we must have s = t = u = 0. Therefore the set of vectors $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly independent.

(e) Let $T = [\mathbf{b}, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3]$. (i) Show that T is invertible, and (ii) there is a diagonal matrix D such that $T^{-1}AT = D$.

Solution. In our case above,

$$T = \begin{bmatrix} 1 & -1 & -1 & -1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix}, \text{ and } \det(T) = \begin{vmatrix} 4 & -1 & -1 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = 4 \neq 0.$$

Hence T is invertible.

$$AT = A[\mathbf{b}, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] = [(a+3b)\mathbf{b}, (a-b)\mathbf{v}_1, (a-b)\mathbf{v}_2, (a-b)\mathbf{v}_3] = TD,$$

where D is a diagonal matrix with a + 3b, a - b, a - b, a - b on the diagonal. Since T is invertible, $T^{-1}AT = D$.

Remarks. First note that $B\mathbf{b} = (4b) \cdot \mathbf{b}$. So $BT = B[\mathbf{b}, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] = [B\mathbf{b}, B\mathbf{v}_1, B\mathbf{v}_2, B\mathbf{v}_3] = [4b\mathbf{b}, \mathbf{0}, \mathbf{0}, \mathbf{0}] = [\mathbf{b}, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] \text{diag}(4b, 0, 0, 0) = T \text{diag}(4b, 0, 0, 0)$, where diag(4b, 0, 0, 0) is a diagonal matrix with 4b, 0, 0, 0 on its diagonal. Thus B is diagonalized by T. Note that $4b \neq 0$, \mathbf{b} cannot be written as a linear combination of $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$. Thus the columns of T are linearly independent and T is invertible. Since A = (a - b)I + B, we are done. Check the following.

$$T^{-1}AT = T^{-1}((a-b)I+B)T = (a-b)I + T^{-1}BT = (a-b)I + \text{diag}(4b, 0, 0, 0) = D.$$

3. Let A, \boldsymbol{x} and \boldsymbol{b} be a matrix and vectors given below. Assume $A\boldsymbol{x} = \boldsymbol{b}$. (35 pts)

$$A = \begin{bmatrix} 3 & -1 & 2 & 0 \\ 1 & 2 & -2 & 5 \\ -1 & 3 & 1 & 1 \\ 2 & 3 & 1 & -2 \end{bmatrix}, \ \boldsymbol{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}, \ \boldsymbol{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}.$$

(a) Evaluate det(A). Briefly explain each step.

Solution. The first 4 steps are exactly the same as in (d). Then [3, 2, -5], [4, 2; 7] and we have the 2×2 determinant by expanding along the first and the second column. The rest are easy.

$$A = \begin{vmatrix} 3 & -1 & 2 & 0 \\ 1 & 2 & -2 & 5 \\ -1 & 3 & 1 & 1 \\ 2 & 3 & 1 & -2 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & -2 & 5 \\ 3 & -1 & 2 & 0 \\ -1 & 3 & 1 & 1 \\ 2 & 3 & 1 & -2 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & -2 & 5 \\ 0 & -7 & 8 & -15 \\ 0 & 5 & -1 & 6 \\ 0 & -1 & 5 & -12 \\ 0 & 5 & -1 & 6 \\ 0 & -7 & 8 & -15 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & -2 & 5 \\ 0 & 1 & -5 & 12 \\ 0 & 5 & -1 & 6 \\ 0 & -7 & 8 & -15 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & -2 & 5 \\ 0 & 1 & -5 & 12 \\ 0 & 5 & -1 & 6 \\ 0 & -7 & 8 & -15 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & -2 & 5 \\ 0 & 1 & -5 & 12 \\ 0 & 5 & -1 & 6 \\ 0 & -7 & 8 & -15 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & -2 & 5 \\ 0 & 1 & -5 & 12 \\ 0 & 0 & 24 & -54 \\ 0 & 0 & -27 & 69 \end{vmatrix}$$
$$= - \begin{vmatrix} 24 & -54 \\ -27 & 69 \end{vmatrix} = - \begin{vmatrix} 24 & -54 \\ -3 & 15 \end{vmatrix} = -6 \cdot 3 \begin{vmatrix} 4 & -9 \\ -1 & 5 \end{vmatrix} = -198.$$

(b) Applying the Cramer's rule and express x₂ and x₃ as quotients of determinants. <u>Do not evaluate determinants.</u> Solution.

$$x_{2} = \frac{\det(A_{2})}{\det(A)}, x_{3} = \frac{\det(A_{3})}{\det(A)} \text{ with } A_{2} = \begin{bmatrix} 3 & 1 & 2 & 0\\ 1 & 2 & -2 & 5\\ -1 & 3 & 1 & 1\\ 2 & 4 & 1 & -2 \end{bmatrix}, A_{3} = \begin{bmatrix} 3 & -1 & 1 & 0\\ 1 & 2 & 2 & 5\\ -1 & 3 & 3 & 1\\ 2 & 3 & 4 & -2 \end{bmatrix}.$$

(c) Let $B = \operatorname{adj}(A)$, the adjugate of A. Determine the (2, 3)-entry of B. <u>Do not evaluate the determinant involved</u>. <u>Solution</u>.

$$B_{2,3} = (-1)^{2+3} \begin{vmatrix} 3 & 2 & 0 \\ 1 & -2 & 5 \\ 2 & 1 & -2 \end{vmatrix} = - \begin{vmatrix} 3 & 2 & 0 \\ 1 & -2 & 5 \\ 2 & 1 & -2 \end{vmatrix}.$$

Let B be the augmented matrix of $A\boldsymbol{x} = \boldsymbol{b}$. Let C be a matrix obtained from B after applying a series of elementary row operations.

$$B = \begin{bmatrix} 3 & -1 & 2 & 0 & 1 \\ 1 & 2 & -2 & 5 & 2 \\ -1 & 3 & 1 & 1 & 3 \\ 2 & 3 & 1 & -2 & 4 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 2 & -2 & 5 & 2 \\ 0 & 1 & -5 & 12 & 0 \\ 0 & 5 & -1 & 6 & 5 \\ 0 & -7 & 8 & -15 & -5 \end{bmatrix}.$$

(d) Write a sequence of operations applied to B to obtain C using [i; c], [i, j], [i, j; c] notation.

 $Solution. \quad [1,2] \to [2,1;-3] \to [3,1;1] \to [4,1;-2] \to [2,4] \to [2;-1].$

(e) Find a 4×4 matrix P such that PB = C. Solution.

$$P = E(2; -1)E(2, 4)E(4, 1; -2)E(3, 1; 1)E(2, 1; -3)E(1, 2) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 2 & 0 & -1 \\ 0 & 1 & 1 & 0 \\ 1 & -3 & 0 & 0 \end{bmatrix}.$$

(f) Express P^{-1} as a product of elementary matrices using the notation E(i;c), E(i,j), E(i,j;c). Solution.

$$P^{-1} = (E(2;-1)E(2,4)E(4,1;-2)E(3,1;1)E(2,1;-3)E(1,2))^{-1}$$

= $E(1,2)E(2,1;3)E(3,1;-1)E(4,1;2)E(2,4)E(2;-1).$

(g) Explain that P in (e) is uniquely determined.
Solution. Let C' be the 4 × 4 matrix consisting of the first 4 columns of C. Since the first four columns of B forms A, we have PA = C'. Since det(A) ≠ 0 in (a), A is invertible. Thus P = C'A⁻¹ and P is uniquely determined.

4. Let
$$\boldsymbol{e}_1, \, \boldsymbol{e}_2, \, \boldsymbol{e}_3, \, \boldsymbol{v}_1, \, \boldsymbol{v}_2 \text{ and } \, \boldsymbol{v}_3 \in \mathbb{R}^3$$
 be as follows. (20 pts)

$$\boldsymbol{e}_1 = \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \ \boldsymbol{e}_2 = \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \ \boldsymbol{e}_3 = \begin{bmatrix} 0\\0\\1 \end{bmatrix}, \ \boldsymbol{v}_1 = \begin{bmatrix} 1\\2\\4 \end{bmatrix}, \ \boldsymbol{v}_2 = \begin{bmatrix} 0\\-1\\1 \end{bmatrix}, \ \boldsymbol{v}_3 = \begin{bmatrix} 2\\3\\8 \end{bmatrix}.$$

(a) Find the reduced row echelon form of the following matrix. (Show work.)

Solution.

$$\begin{bmatrix} 1 & 0 & 2 & 1 & 0 & 0 \\ 2 & -1 & 3 & 0 & 1 & 0 \\ 4 & 1 & 8 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 1 & 0 & 0 \\ 0 & 1 & 0 & -4 & 0 & 1 \\ 0 & -1 & -1 & -2 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 1 & 0 & 0 \\ 0 & 1 & 0 & -4 & 0 & 1 \\ 0 & 0 & -1 & -6 & 1 & 1 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 0 & 2 & 1 & 0 & 0 \\ 0 & 1 & 0 & -4 & 0 & 1 \\ 0 & 0 & 1 & 6 & -1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & -11 & 2 & 2 \\ 0 & 1 & 0 & -4 & 0 & 1 \\ 0 & 0 & 1 & 6 & -1 & -1 \end{bmatrix}.$$

- (b) Using (a), explain that $\{\boldsymbol{v}_1, \boldsymbol{v}_2, \boldsymbol{v}_3\}$ is linearly independent. Solution. Let $B = [\boldsymbol{v}_1, \boldsymbol{v}_2, \boldsymbol{v}_3]$. Then $\{\boldsymbol{v}_1, \boldsymbol{v}_2, \boldsymbol{v}_3\}$ is linearly independent if and only if B is invertible. B is invertible if and only if its reduced echelon form is I. This is the case as we have seen above. Hence $\{\boldsymbol{v}_1, \boldsymbol{v}_2, \boldsymbol{v}_3\}$ is linearly independent.
- (c) Find the standard matrix A of a linear transformation $T : \mathbb{R}^3 \to \mathbb{R}^3$ such that $T(\boldsymbol{v}_1) = \boldsymbol{e}_1, T(\boldsymbol{v}_2) = \boldsymbol{e}_2$ and $T(\boldsymbol{v}_3) = \boldsymbol{e}_3$. Solution. As in the previous problem let $B = [\boldsymbol{v}_1, \boldsymbol{v}_2, \boldsymbol{v}_3]$. Then by out as-

Solution. As in the previous problem let $B = [v_1, v_2, v_3]$. Then by out assumption, we have

$$AB = A[v_1, v_2, v_3] = [Av_1, Av_2, Av_3] = [e_1, e_2, e_3] = I.$$

Thus B is invertible and $A = B^{-1}$ and by (a)

$$B = \begin{bmatrix} -11 & 2 & 2\\ -4 & 0 & 1\\ 6 & -1 & -1 \end{bmatrix}.$$